L7: Uncertainty in geographic information

Introduction to final projects

Longley et al., 2005, Geographic Information Systems and Science: - ch. 6: Uncertainty

Uncertainty in geographic information:

- What is uncertainty?
- U1: Uncertainty in the conception of geographic phenomena
- U2: Uncertainty in the measurement and representation of geographic phenomena
- U3: Uncertainty in the analysis of geographic phenomena
- Dealing with uncertainty

Introduction to the final project

What is uncertainty?

It is impossible to make a perfect representation of the world, so **uncertainty** about it is **inevitable**.



L7: Uncertainty Coogle Earth



L7: Uncertainty Soogle Earth



L7: Uncertainty

Soogle Earth



Data quality



Data product is usable only when a certain level of reliability is reached.

Important: to present information about the quality of original data and the uncertainty from the processing steps to the user.

Aspects of data quality:

Lineage – when the data was collected, what processing was used, etc.

- **Positional accuracy** – how far is an object from its real position

- Attribute accuracy – what is the accuracy of attributes' values for an object

- Logical consistency – do the lines intersect in a point, are the areas closed polygons, etc.

Completeness – is the data complete for the whole collection area

Where does uncertainty occur?



U1: Uncertainty in concepts









Fuzzy approaches



Fuzzy model for imprecise soil polygon boundaries

Soil mapping:

- soil type classification
- defining soil polygon boundaries

sparse sampling in Finland due to large extent of the country.

Defining soil boundaries in Finland between actual sampling sites: manual interpretation by soil suveyors using areial photos geological maps topographical map knowledge about geomorphology

Different surveyors produce different maps.

Fuzzy modelling for imprecise soil boundaries

Soil boundaries are not crisp in real world.

Fuzzy modelling is a way to take into account the gradual change between soil types and represent the uncertainy in soil polygon mapping.



Case study – Vampula area

Definitions of membership functions for fuzzy modelling based on specific soil characteristics of the study area.

Rules for:

 transitional zone -> varies according to soil type

- zone width -> based on expert knowledge



150 km

75

Norwegian

SWEDEN

150 m

Ivalo*

Rovaniemi

Barents

San

RUSSIA

0

Fuzzy map



Crisp boundaries between soil polygons





Risk maps for soil pH < 4.5



Okavango DEM





Figure 12b. Elevation profile along the western shoreline of palaeo-lake Makgadikgadi. The bold line shows the estimated elevation, while the two enveloping lines represent the standard deviation. Breaks occur in the lines where the palaeo-shoreline cannot be identified on the satellite image.

shoreline cannot be identified on the satellite image.

U2: Uncertainty in the measurement and representation

Representational models filter reality & uncertainty differently:

Uncertain generalised coastline



Example of an uncertain generalised coastline: fjords on a map of Scandinavia



Statistical models of uncertainty

For nominal attributes

How to measure the accuracy of nominal attributes? e.g., a vegetation cover map

The confusion matrix

compares recorded classes (the observations) with classes obtained by some more accurate process, or from a more accurate source (the reference)



L7: Uncertainty

Example of a **misclassification or confusion matrix**. A grand total of 304 parcels have been checked. The rows of the table correspond to the land use class of each parcel as recorded in the database, and the columns to the class as recorded in the field. The numbers appearing on the principal diagonal of the table (from top left to bottom right) reflect correct classification.

Reference (correct) classes

		Α	В	С	D	Е	Total
	Α	80	4	0	15	7	106
Obsorved	В	2	17	0	9	2	30
(assigned)	С	12	5	9	4	8	38
Classes	D	7	8	0	65	0	80
	E	3	2	1	6	38	50
	Total	104	36	10	99	55	304

	Α	В	С	D	E	Total
Α	80	4	0	15	7	106
В	2	17	0	9	2	30
С	12	5	9	4	8	38
D	7	8	0	65	0	80
E	3	2	1	6	38	50
Total	104	36	10	99	55	304

How good is the classification?

Percent correctly classified parcels:

- total of diagonal entries divided by the grand total, times 100
- in this case: 209/304*100 = 68.8%

Kappa statistic = a special index to evaluate how good the assignment is: parmalized to range from 0 (chappe) to 100

- normalized to range from 0 (chance) to 100
- evaluates to 58.3% in this case

Okavango Delta - Botswana -Land cover classification



Water = 2.5 m below reference level



Permanent Swamp = 2.0 m below reference level



Primary floodplain = 1.5 m below reference level



Secondary floodplain = 1.0 m below reference level



Grassland = reference level



Salt pan = 0.5 m below reference level



Occasionally flooded grassland = 0.5 m below reference level



Salt pan = 0.5 m below reference level



Riverine forest = 1.2 m above reference level



Dry woodland = reference level



Dry woodland = reference level



Okavango Delta knowledge based classification



Landcover ecoregions

inside to														
	Wat	PSC	PFP	S FP	GL	SP	RF	Aca	Mop	Com	Total	ErrorC		
Wat	861	20	21	.0	0	0	1	0	0	0	903	0.046	Wat	Water
PSC	15	1000	234	21	0	5	106	1	0.	0	1381	0.276	PSC	Permanent swamp communities
PFP	9.	135	980	279	27	0.	160	2	-30	3	1595	0.386	PFP	Primary flood plain
S FP	1	14	57	149	2	0	78	8	0	1	310	0.519	S FP	Secondary flood plain
GL	0	0	97	76	191	11	46	328	56	2	807	0.763	GL	Grassland
SP	Ω.	0	0	0	71	89	2	73	15	2	261	0.624	SP	Sparse grassland/salt crust
RE	4	7	13	5	4	3	382	190	0	20	628	0.392	RE	Riparian forest
Aca	43.	11	0	2	0	4	34	362	57	3	462	0.216	Aca	Acaria woodland
Mop	10.	0	0	0	- 10	0	14	79	[TH1	D.	1.99	0.467	Mop	Mopane woodland
Com	.0		0	0	. 0	- 0	3	2	1	0	6	1.000	Com	Combretum woodland
Total ErrorO	890	0.150	1402 0_301	532 0.720	295 0.352	121	826 0.538	0.654	235 0.549	1,000	6553	0,370	ErrorO ErrorO	Error of commission Error of omission

Table 5. Error matrix and accuracy for the rule-based classification in 10 classes (the columns represent the ground-data image and the rows the classified image).

Table 6. Error matrix and accuracy for the rule-based method in six classes (the columns represent the ground-data image and the rows the classified image).

	Wat	PSC	FP	GL	SP	For	Total	ErrorC		
Wat	861	20	21	19	0	I	903	0.046	Wat	Water
PSC	15	1000	255	.0	5	107	1382	0,276	PSC	Permanent swamp communities
FP	10	149	1465	20	0	252	1935	0.231	FP	Flood plain
GL	D	0	173	191	11	-432	807	0.763	GL	Grassland
SP	10	0	0	71	98	92	261	0.624	SP	Sparse grassland/salt crust
For	4	7	20	4	7	1253	1295	0.032	For	Forest
Total	890	1170	14/34	295	121	2137	6553		ErrorC	Error of commission
ErrorO	0.033	0,150	0.242	0.352	0.190	0.414		0.251	ErrorO	Error of omission

The abbreviations correspond to the six aggregated ecoregion classes. Overall accuracy = 74.3%; Kappa index of agreement = 0.67.

Figure 3. Example of fuzzy membership function to slope. Between slopes 2 and 6 the membership is 1, whereas it changes gradually from 0 to 1 between slope 0 and 2 and 11 and 6 respectively. In guide the above fuzzy membership function is written "Whenimg @ 0 2 TO 6 11 Slope", the Boolean logic is written "Whenimg @ 2 TO 6 Slope".

Table 1. Command structure in guide (forest in the example can either be classified as a lumped category, or the two observations can be separately classified, making it possible to include several forest types in one rule).

command	Followed by	Example - Boolean logic	Example - fuzzy logic
WHENIMG	= category "map" < category "map"	= 3 4 soil > 0 300 DEM	= 3 4 soil >0 40 300 500 DEM
	 > category "map" @ categ TO categ "map" + row nr TO row nr * column nr TO col nr 	< 30 20 slope @ 10 TO 40 20 TO 30 LAI + 0 TO 150 100 TO 250 * 100 TO 500 400 TO 600	< 50 30 30 20 slope @ 0 10 TO 40 50 10 20 TO 30 40 LAI + 0 0 TO 150 300 50 100 TO 250 300 * 50 100 TO 500 600 200 400 TO 600 700
SAVEIMG	# category "name"	# 5 forest	# 5 forest

Transformations fel vid varpning av raster jämfört med vektor

Statistical models of uncertainty For interval/ratio attributes Measurements of attribute values are distorted by small amounts = errors Uncertainty expressed with two concepts Accuracy = the amount of Precision distortion from the true value the variation among also the amount of detail in the repeated measurements reporting of a measurement

The term *precision* is often used to refer to the repeatability of measurements. In both diagrams six measurements have been taken of the same position, represented by the center of the circle. On the left, successive measurements have similar values (they are *precise*), but show a bias away from the correct value (they are *inaccurate*). On the right, precision is lower but accuracy is higher.

The primary measure of accuracy in map accuracy standards and GIS databases:

RMSE = Root Mean Square Error = the square root of the average squared error

For practical purposes: approximately equal to the absolute value of the average error in each observation

Additional measure of accuracy:

How errors are **distributed in magnitude**?

How many are small, how many are large?

Unbiased measurements:

errors follow a normal distribution (Gaussian curve), with mean=0 (there is approximately the same amount positive and negative errors – positive and negative errors cancel each other out)

The Gaussian or Normal distribution. The height of the curve at any value of *x* gives the relative number of observations with that value of *x*. The area under the curve between any two values of *x* gives the probability that observations will fall in that range. The range between -1 standard deviation and +1 standard deviation is in blue. It encloses 68% of the area under the curve, indicating that 68% of observations will fall between these limits.

Uncertainty in the location of the 350 m contour based on an assumed RMSE of 7 m. The Gaussian distribution with a mean of 350 m and a standard deviation of 7 m gives a 95% probability that the true location of the 350 m contour lies in the colored area, and a 5% probability that it lies outside.

U3: Uncertainty in the analysis

Uncertainties in data

Uncertainties in the results of the analysis

Almost every input to a GIS is subject to error and uncertainty.

That is not always the case in practice!

In principle, every output should have confidence limits or some other expression of uncertainty.

Soil map + uncertainty of borders

Dealing with uncertainty

It is easy to see the importance of uncertainty in GIS, but much more difficult to deal with it effectively.

Basic principles for dealing with uncertainty:

- Uncertainty is inevitable in GIS.
- Data obtained from others should never be taken as truth. Instead, efforts should be made to determine quality.
- Effects on GIS outputs are often much greater than expected. This is important, as people tend to regard computer outputs as the truth.
- Use as many sources of data as possible. Cross-check them for accuracy
- Be honest and informative in reporting analysis results. Add warnings and cautions.

Final project – E8

Task: solve GIS problems similar to the ones you have solved during the exercises

Work should be done in groups of 2-3 students (same as for all the exercises). All students in each group are required to take part in the presentation.

However, to keep things from being too repetitive during presentations:

- maximum 3 groups per each topic proposal
- topics allocated on a first-come first-serve basis

Decide what you want to do and send me an email with your selected topic.